



Autopilot Servo Installation Guide

RV6, RV7, RV9 Pitch

This product is not approved for installation in type certificated aircraft

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SERVO MOUNTING INSTRUCTIONS – RV-6/7/9 FUSELAGE PITCH KIT

Kit Contents		
Dynon Part #	QTY	Part Description
100836-000	2	Large Male Rod End
100868-000	1	RV6,7,9 Pitch Bracket
100966-002	1	Aluminum Pushrod Tube - 4.0"
100975-002	2	AN315-4R Jam Nut
100976-011	2	AN365-1032A Nylon Insert Locknut
100977-000	2	AN970-3 Large Flat Washer
100978-003	8	AN960-10 Small Flat Washer
100979-002	3	MS35333-39 #10 Internal Star Washer
100981-000	3	AN3H-3A Bolt - 3/8"
100981-006	1	AN3H-11A Bolt - 1 1/8"
100981-007	1	AN3H-12A Bolt - 1 1/4"
100982-007	1	Aluminum Spacer - 0.250"

The RV-6/7/9 fuselage pitch servo mounting kit includes a mounting bracket, pushrod linkage, and most of the required fasteners to mount the servo and properly link it to the aircraft control system. All Dynon-supplied parts are illustrated in dark grey to distinguish them from existing aircraft hardware. Refer to the drawing to locate the servo mounting bracket, and remove existing fasteners as needed from that location to allow clearance for the bracket to sit flush against the spar. The flange at the bottom of the bracket can be used to rivet through the fuselage floor, or this flange can be trimmed off. It is up to the installer to fasten the bracket using appropriate hardware, whether that be match drilling the holes along the spar and installing rivets or using AN bolts and nuts to secure the bracket in place (these fasteners are not available from Dynon).

With the bracket installed in the aircraft, the bell crank must be drilled. Refer to the drawing for dimensions, and use a supplied AN960-10 washer as a support between the two halves of the bell crank to avoid crushing when the linkage is fastened.

Install the 3 AN3H-3A bolts, MS35333-39 star washers, and AN960-10 flat washers to secure the servo to the bracket per the drawing, noting the orientation of the servo output arm. All AN bolts supplied by Dynon have drilled heads for use with safety wire. With the servo and bell crank additions in place, torque all fasteners back to original installation specifications and add safety wire where needed.

With the servo installed, the linkage needs to be assembled. Refer to the illustration and follow proper rod end installation techniques. Screw at least half of the threads on each rod end into the push rod. To prevent the possibility of the servo arm going over-center, the servo arm must **not** travel more than a total of +/-60° from neutral throughout the control system's range of travel. The linkage should be installed as close to the Dynon recommendation as possible, as

changes will affect geometry. Dynon suggests installing the linkage at the outer-most hole of the servo arm. Changing this location will affect servo torque output, servo arm travel, control surface resolution, and the amount of force required to shear the safety screw, and should only be changed if the installer has an understanding of these implications. See the diagram on the following page which illustrates the linear travel and available force for each mount point on standard-arm servos.

Thread both large rod ends with jam nuts into the supplied 4.0" tube. Mounting of the linkage to the servo arm will include the AN3H-12A bolt, AN970-3 large diameter flat washer (for capturing the rod end bearing), 2 AN960-10 flat washers, the 0.250" aluminum spacer, and the AN365-1032A lock nut. The other end of the linkage will require the same type of stack-up, using the shorter AN3H-11A bolt (no spacer at this end) and capturing the washer sandwiched between the halves of the bell crank. Note the orientation of this bolt is flipped for clearance when compared to the bolt installed in the servo arm

The distance between the servo arm and the control system attachment point must allow for the angle between the servo arm and the push rod to be at approximately 90° when the controls are at neutral. Use the adjustability in the rod ends to achieve this, and then tighten the jam nuts to lock the rod ends in place. Installers should always keep in mind the range of motion of the servo. Total servo arm travel is limited, but verify the arm/linkage do not interfere with anything during the full motion of the control stick. The built in control stops of the aircraft will limit the servo arm travel when installed correctly. We recommend the use of the optional Range of Motion Limiting Bracket, supplied with the servo to eliminate the chance of the servo arm going over-center. This bracket should not be used as a normal stop; the aircraft's built-in stops should always be the primary range limit.

Your servo(s) and AP74/76 (if ordered) came with a CD containing the latest documentation for all Dynon products (also available at dynonavionics.com). Please read through that documentation to understand the wiring and configuration process for your Autopilot system. We also maintain a collaborative set of this documentation, which is often updated with new information by both Dynon and fellow builders. Visit wiki.dynonavionics.com to view and contribute to the latest version of these documents.

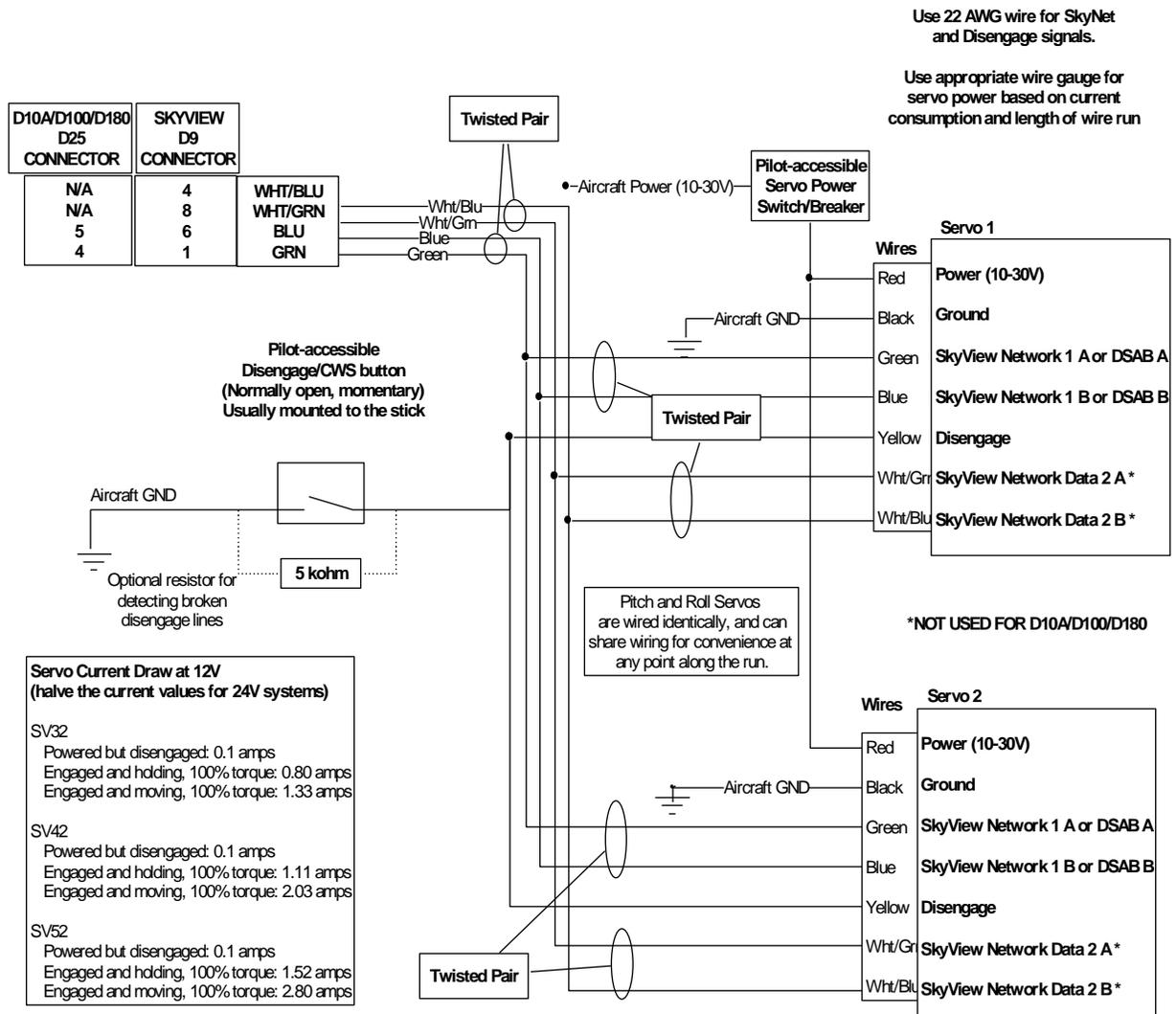
You can also visit forum.dynonavionics.com to discuss and share installation notes, pictures, and suggestions with other builders.



Neglecting to properly install and/or use Dynon autopilot hardware may result in failures which could cause loss of aircraft control resulting in aircraft damage, personal injury or death.

Wiring Overview

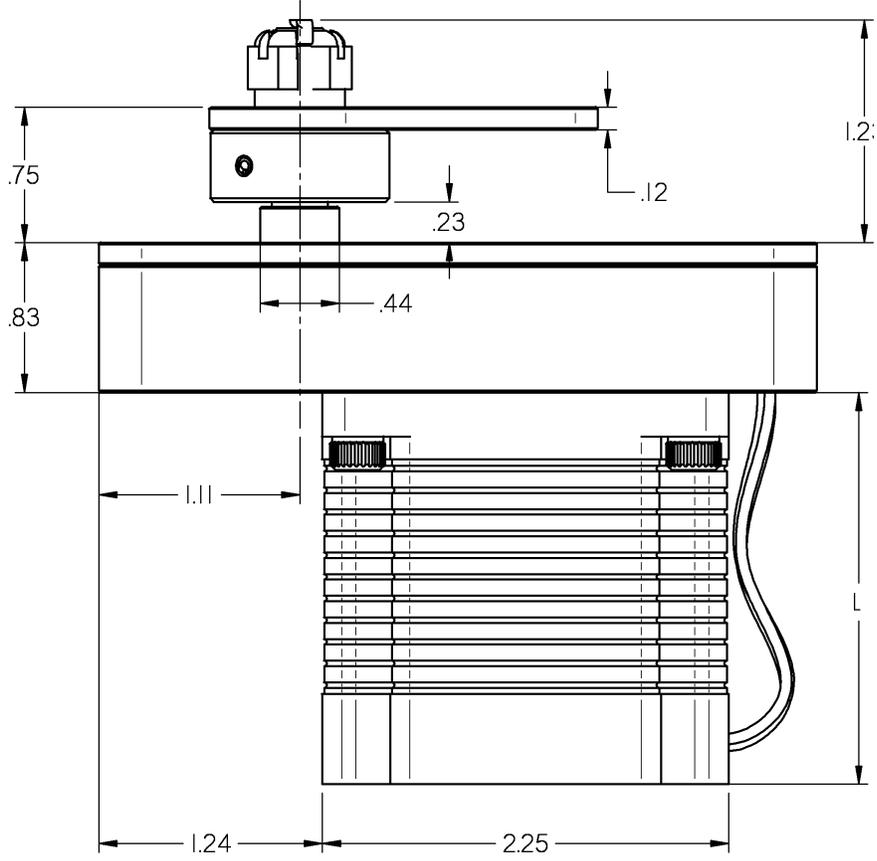
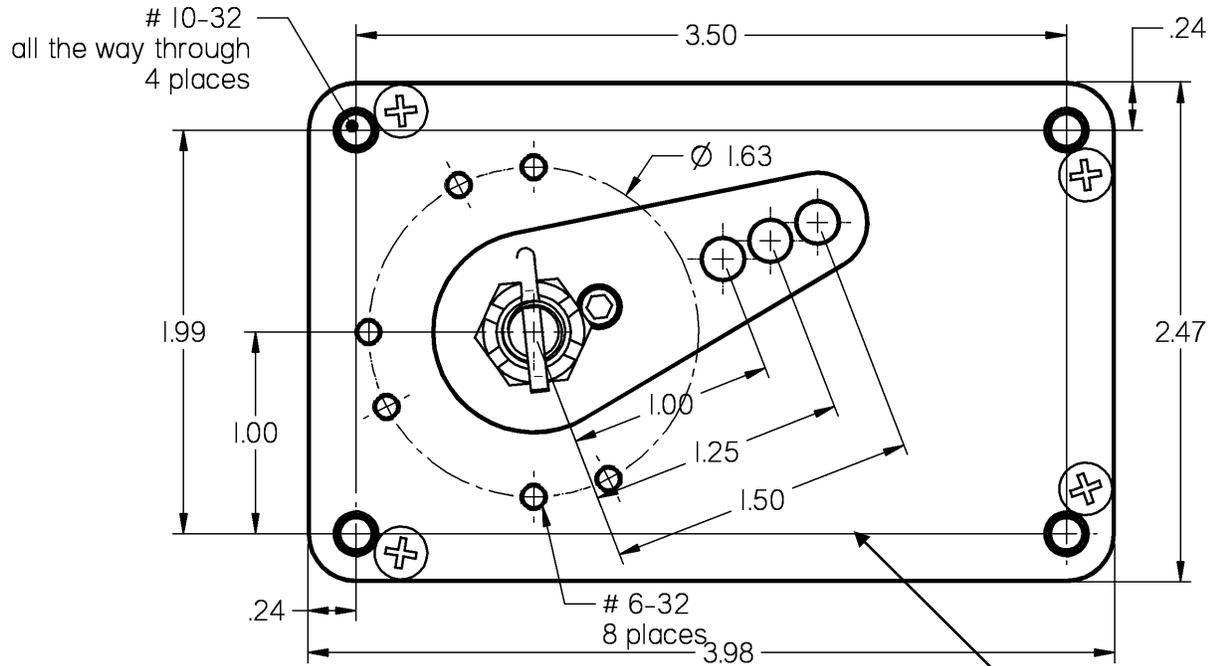
The following diagram provides an overview of the autopilot-specific wiring installation. For the complete set of wiring and configuration instructions, please see the latest Installation Guide for your Dynon EFIS product. For a SkyView system please reference the **Autopilot Servo Installation, Configuration, and Calibration** chapter of your SkyView System Installation guide. For EFIS-D10A, EFIS-D100 or FlightDEK-D180 please reference the **Autopilot Installation and Configuration** chapter of each respective Installation Guide.





Servo Dimensions

Use the following dimensions (in inches) for reference when planning and implementing your installation.



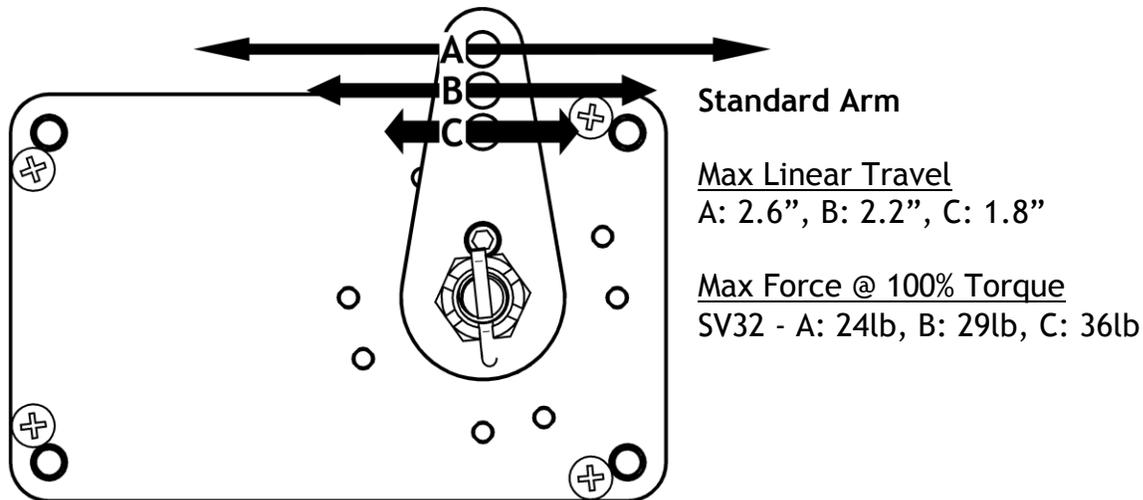
Long-arm variants
(not needed in most
installations) have
linkage mount holes
at 1.5", 1.75", and
2.0"

	L	Weight
SV32	2.17"	2 lb
SV42	3.10"	3 lb
SV52	4.02"	4 lb

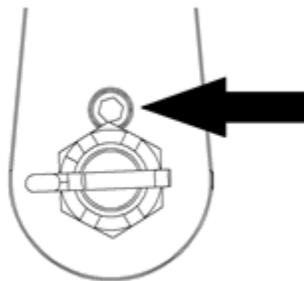
Linkage mount position force and travel

The diagram below illustrates the maximum travel and force available at each linkage mounting point. As can be seen, the closer you mount the linkage to the shaft, the more force the servo can deliver. However, this also means the travel of the arm is shorter. Again, ensure that the servo arm is nowhere near going over-center throughout the entire range of the control system.

Position A should be used in most RV-6/7/9 pitch installations. Modify mount position with caution and take all precautions to ensure that a near over center condition cannot occur.



- ⚠ The autopilot safety shear screw should NEVER be removed or adjusted during this operation. If the shear screw has broken and needs replacement, there is specific documentation available for this purpose at <http://docs.dynonavionics.com>.



Mounting Drawings

The following pages provide detailed views of the mounting and assembly of the servo and this kit.

